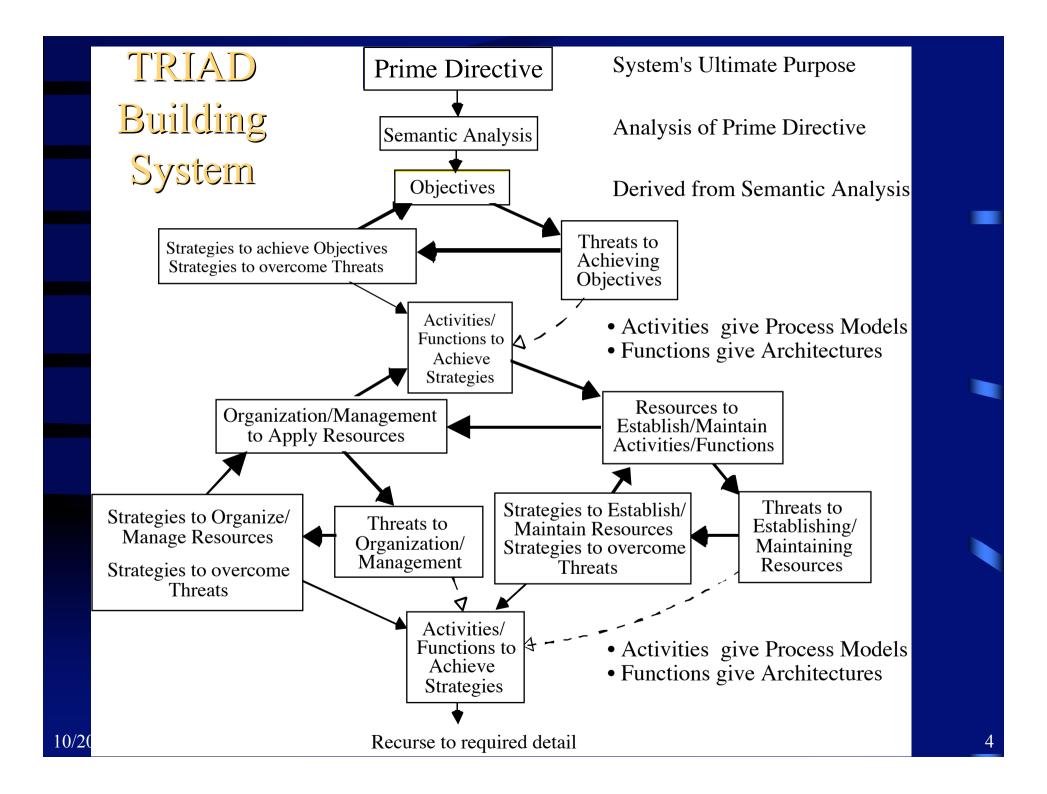
Conceive Potential Solutions

Derek Hitchins

Starting with a Blank Space

- Maintain the highest level of abstraction;
- Make as few assumptions as possible;
- Challenge any and all presumptions;
- Identify obstacles to solution;
- Identify alternative ways to overcome obstacles;
- Creating alternative solution "maps"
- Model alternative solution concepts dynamically;
- Explore:
 - counterintuitive behaviour,
 - reactions from other systems,
 - resource demands, and likely costs;
- Select the "best" conceptual solution, where best may mean any or all of:
 - simplest, cheapest, best quality, lowest risk, most appealing, most exciting, most needed, and so on.

Concept Development The TRIAD Building System



Using the TRIAD Building System —the Prime Directive

- Prime Directive = ultimate statement of purpose
- For Mobile Land Force, might be:
 - 1. To neutralize enemies in open desert and tundra regions around the world
 - 2. To deter potential enemies from operating in desert and tundra regions
- 1 subsumes 2, therefore 1 preferred
- PD is intentionally bare, with minimal assumptions

Semantic Analysis

• To neutralize ...

• To render ineffective...

• enemies in...

• those opposed to the US as identified by UN directive ABC existing and/or operating in...

open desert and...

• open, desolate, largely uninhabited tracts...

• tundra regions...

• and Arctic plains with permanently frozen subsoil, lichens, mosses, and dwarfed vegetation...

• ...around the world

wherever sanctioned by the UN

N.B. Definitions of desert and tundra areas quite inadequate.

Objectives from Semantic Analysis Implicit Objectives

Semantic Analysis

- To render ineffective...
- those opposed to the US as identified by UN directive ABC existing and/or operating in...
- open, desolate, largely uninhabited tracts...
- and Arctic plains with permanently frozen subsoil, lichens, mosses, and dwarfed vegetation...
- wherever sanctioned by the UN

To deploy swiftly

- To operate over wide areas radially different environments, temperatures, going, etc.
- To move rapidly to scenes of incursion/activity
- To identify legitimate enemies specifically
- To engage and deter, or overcome
- To operate within a UN mandate at all times

Strategies

Objectives

- To deploy swiftly
- To operate over wide areas radically different environments, temperatures, going, etc.
- To move rapidly to scenes of incursion/activity
- To identify legitimate enemies specifically
- To engage and deter, or overcome
- To operate within a UN mandate at all times

Strategies to Achieve Objectives

- Air transportable
- Air deliverable
- High powered, high speed, all terrain vehicles
- UMAs for remote identification and engagement where appropriate
- Vehicles to operate and fight on the move as an integrated unit, for speed, area coverage, avoidance of detection
- Fleet formation management to reduce enemy threat open and tight, etc.
- Some vehicles to be self steering, but under control of personnel in nearby vehicle/command post.

Strategies to Overcome Threats

Objectives

- To deploy swiftly
- To operate over wide areas radically different environments, temperatures, going, etc.
- To move rapidly to scenes of incursion/activity
- To identify legitimate enemies specifically
- To engage and deter, or overcome
- To operate within a UN mandate at all times

Strategies to Overcome Threats to Achieving Objectives

- Pre-deployed cadre forces in area
- Some WS/vehicles specialized for hot, wet, cold, ice, etc. conditions
- Use of non-lethal force to neutralize
 - Use of armoured UMAs to accelerate ahead of ground force
 - Equipped: psy-ops, loudspeakers, leaflets,
 stun weapons, non-lethal anti-riot weapons
 - Equipped: fuel-air and thermobaric weapons (to warn as well as neutralize) +short-range electromagnetic pulse (SREMP)
 - Equipped: canon, anti-tank missile, etc.,
 anti-sniper lasers, enhanced remote
 ethnic/nationality laser identification

From Strategies to Functions

Strategy

- Air transportable
- Air deliverable
- High powered, high speed, all terrain vehicles
- UMAs for remote identification and engagement where appropriate
- Vehicles to operate and fight on the move as an integrated unit, for speed, area coverage, avoidance of detection
- Fleet formation management to reduce enemy threat open and tight, etc.
- Some vehicles to be partly robotic, but
 under control of personnel in nearby
 vehicle/command post.

Implied Function

- Dedicated air transport
- Palletised low-altitude insertion
- Highly-specialized vehicles
- UMA launch, control, operate and recover—on the move!
- UMA turn-round, repair, refuel, rearm, re-equip—on the move!
- Formation control: reacts to threat, disperses, closes, re-arranges vehicle formations in face of threat from terrain and enemy
- Mobile repair units, operating on the move
- Short-range communications for security, "silent" running

From Strategies to Functions

Strategy

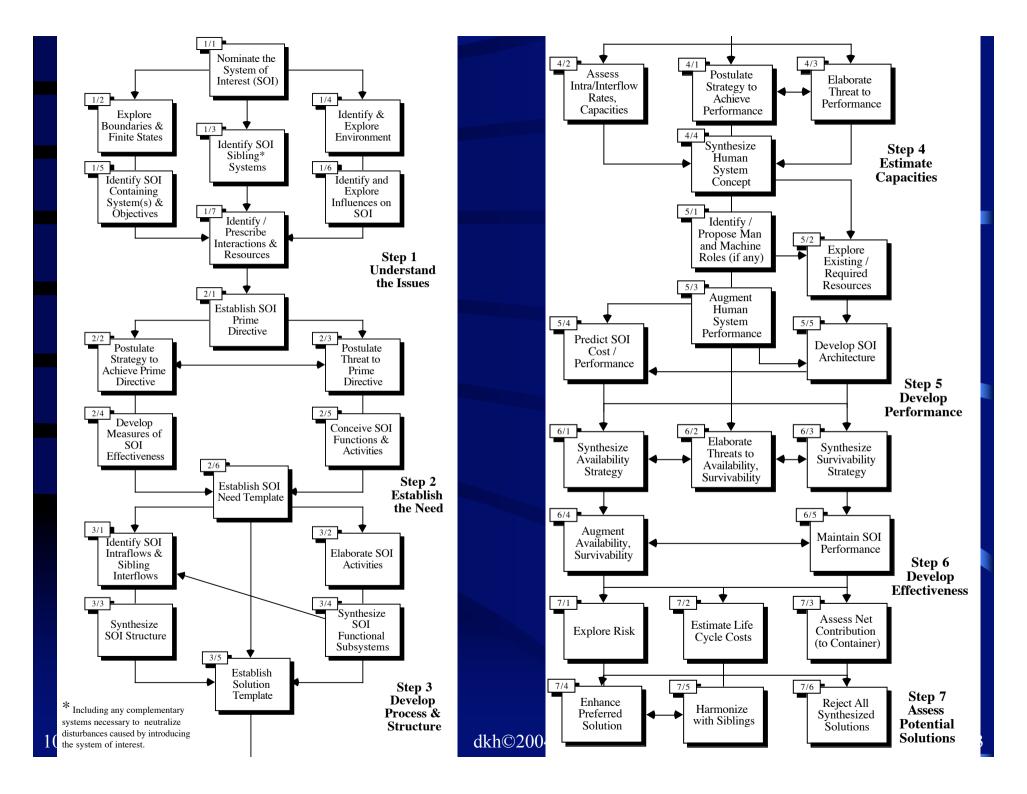
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 - Equipped: canon, anti-tank missile, etc., anti-sniper lasers, enhanced remote ethnic/nationality laser identification

Implied Function

- Cadre forces maintenance, communications and intelligence
- Special vehicle support
- Lethal weapons training/practice
- Non-lethal weapons training
- Fuel-air and thermobaric weapons training/practice
- Human target identification
- Sniper location
- Real-time control of Rules of Engagement

Putting Flesh on the Bones The Seven-Step Continuum

A codified approach, ensuring thoroughness, coverage and speed.



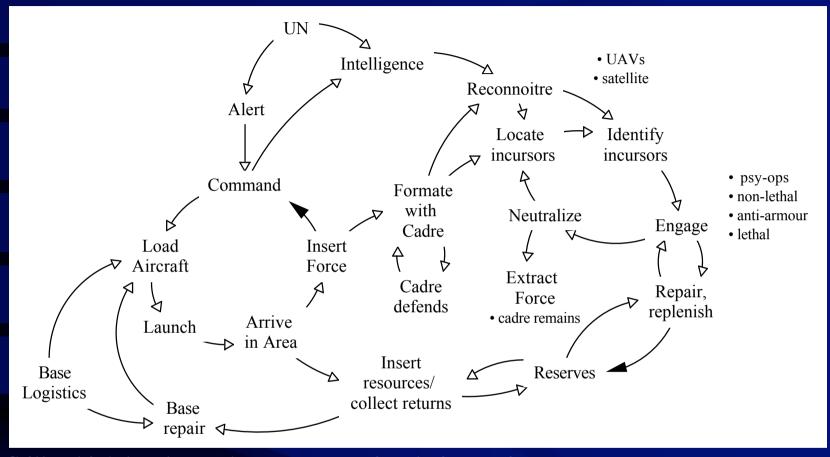
SSC - Step 1

- 1/1 Nominate System of Interest: Mobile Land Force 2010
- 1/2 Explore Boundaries and Finite States: Complementary set of interacting, all terrain, fighting vehicles operating multiple UAVs after the manner of a land-based aircraft carrier task force. States: training, standby, operational, recovery, turnround & repair
- 1/3 Identify SOI Sibling Systems: air transport, air insertion, air recovery, satellite intelligence, satellite comm/nav, logistic support, repair facilities, vehicle recovery
- 1/4 Identify & Explore Environment: desert & tundra, varied, wide temperature variation, plains with rocky outcrops, frozen lakes, little vegetation, v.sparsely populated if at all
- 1/5 Identify SOI Containing System and Objectives: US Global Peace Command. To neutralize enemy incursions into UN designated global deserts and tundra
- 1/6 Identify and Explore Influences on SOI: Political desire to operate without loss of US lives. UN desire to operate without loss of any lives. US belief in advanced hi-tech weapon systems. US defense business interest in developing advanced, non-lethal weapons
- 1/7 Identify and Prescribe Interactions and Resources: Air Transport and Insertion; resupply; intelligence; RoE; fuel, weapons and consumables; UAVs; trained operators; repair staff, logisticians, communications, satellite navigation, etc., etc.

SSC-Step 2

- 2/1 Establish SOI Prime Directive: to neutralize enemy incursions into UN designated desert and tundra swiftly and with minimal loss of life
- 2/2 Postulate Strategy to achieve PD: see TRIAD Building System
- 2/3 Postulate Threat to PD: see TRIAD Building System
- 2/4 Develop Measures of SOI Effectiveness:
 - a) time to scene b) time to neutralize c) degree of neutralization d) Blue casualties e) Red casualties f)
 operation costs & cost effectiveness g) cost exchange ratios
 h) casualty exchange ratios
- 2/5 Conceive SOI Functions and Activities: Time for CONOPS!
- 2/6 Establish SOI Needs Template:

Mobile Land Force CONOPS



- Still at high level—we have yet to posit solution options...
- Note continuity of operations: once started, continues until all "incursors" neutralized
- This CLM may be simulated, using a non-linear dynamic modelling tool, to investigate:
 - Time delays logistics Effects of operations on reserves, maintenance, and vice versa
- Results of simulation (= operations analysis) may invoke changes to CONOPS
 - e.g. should transport aircraft be on airborne QRA to minimize delays?

2/5 Conceive SOI Functions and Activities

Functions to Achieve Strategies

- Cadre forces maintenance, communications and intelligence
- Special vehicle support
- Lethal weapons training/practice
- Non-lethal weapons training
- Fuel-air and thermobaric weapons training/practice
- Human target identification
- Sniper location
- Real-time control of Rules of Engagement
- Dedicated air transport
- Palletised low-altitude insertion
- Highly-specialized vehicles
- UMA launch, control, operate and recover—on the move!
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Operational functions from CONOPS

- Intelligence development
- Reconnaissance
- Command & control
- Force extraction
- Base resupply / repair
- Force self defense

- Lists at left and above derived from operational considerations
- Ignore hosts of internal functions essential to establish and maintain any mobile, yet unified, fighting force
- These can be derived using a Generic Reference Model (GRM)

2/6. Requirements Template-Generic

- Now able to develop a Requirements Template
- Generic Version shows what we have done, and what remains...

S-O-I Prime Directive Semantic Analysis of Prime Directive					
Strategy for Achieving Prime Directive Behaviour Strategy Management Set					
Aggression Discretion Co-operation	Strategy options Unifying concepts Innovative approaches	Mission management Viability management Resource management			
Measures of S-O-I effectiveness Performance Availability Survivability	Negative contribution factors Cost Mass/weight/volume Complexity Failure modes/criticality	Threat to achieving PD External Internal Environmental Political/economic/ social/technical			

GRM—Doing

Internal Architecture Generation Table						
Mission Management		Viability Management		Resource Management		
Management of		Management of		Management of		
GRM	SOI	GRM	SOI	GRM	SOI	
–information	Com. centre Image Centre	-synergy	Formation management C2	acquisition	CPRM Base Resupply Training	
objectives	CPRM	survival	Formation management Self Defense System	storage	Logistic support vehicles Ready use stores	
strategy & plans	Command & Control (C2)	evolution	Performance Recording Systems	distribution	Mobile Distribution Fleet	
execution	C2	homeostasis	Climate control	conversion		
cooperation	C2	maintenance	Mobile maintenance teams	disposal	CPRM	

CPRM: Contingency Planning and Resource Management

GRM—Thinking

Internal Architecture Generation Table					
Cognition Management Management of		Selection Management Management of		Stimulation Management Management of	
GRM	SOI	GRM	SOI	GRM	SOI
tacit knowledge	Desert & tundra combat experts OJT	-nature	Psychological monitoring counselling	motivation	Command and Control
world models	Maps, satellite imagery, cultural perception	experience	"Simulate before activate" practice	activation	Command and Control
		constraint	Rules of Engagement Discipline		

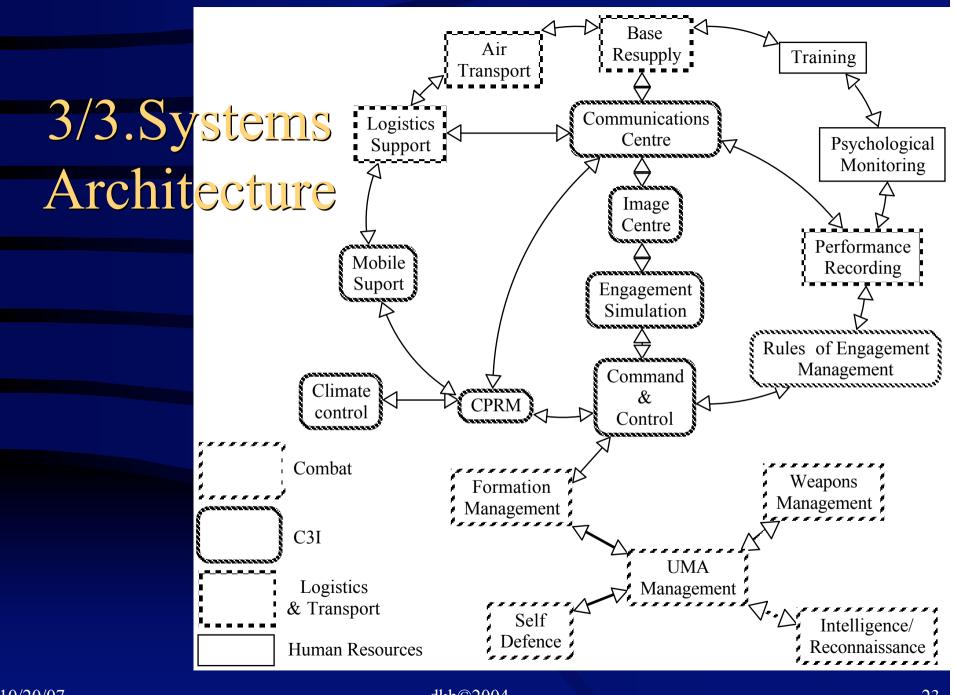
3/2. Land Force 2010. Omissions Identified

Clim Contr	1	J ?	
Wpns Man	2	S 1	
Int/Recce	3	R 1	
UMA Man	4	1 1 Q 1	
Self Def	5	1 P 1	
Formate Man	6	1 0 1	_
C and C	7	1 N 1	?
Engage Sim	8	1 M 1	
Image Centre	9	1 L 1	
Mobile Sup	10	H 1 1	
CPRM	11	? 1 I 1	
Log Supp	12	1 G 1 1	
Comm Centre	13	1 11K 1	1
Air Transp	14	1 F 1	
Base Resup	15	1 1 E	1
Training	16	1	D 1
Perf Rec	17	1	1 C 1 1
Psych Mon	18	9	1 B
ROE Man	19	?	1 A

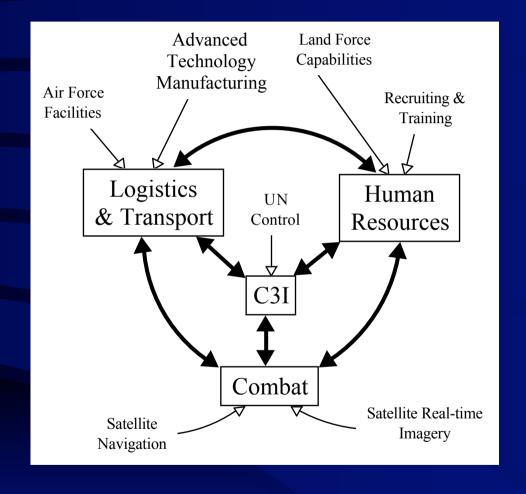
3/4. Interacting Subsystems

	Wpns Man	1	S 1
Combat	Int/Recce	2	R 1
Combat	UMA Man	3	1 1 Q 1
	Self Def	4	1 P 1
	Formate Man	5	10 1
	Clim Contr	6	J 1
	Engage Sim	7	M 1 1
COL	C and C	8	1 1 N 1 1
C31	Image Centre	9	1 L 1
	CPRM	10	1 1 I 11
	ROE Man	11	1 A 1
	Mobile Sup	12	1 H 1
	Comm Centre	13	11 K11 1
Lagistics Pr	Log Supp	14	11G 1
Logistics &	Perf Rec	15	1 1 C 11
Transport	Air Transp	16	1 F 1
1	Base Resup	. 17	
II D	Training	18	1 1 D
Human Resources	Psych Mon	19	1 B

C3I: Command, control, communications and intelligence



3/1.Systems Overview



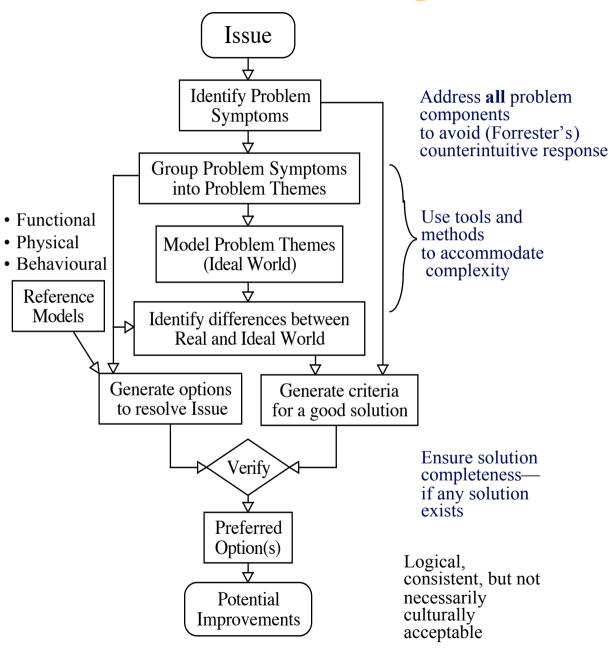
3/5. SOI Solution Template (Generic)

OPTIONS

		1	2	3	4
E F E C T I V E N E S S	PERFORMANCE - Container's Objectives				
C O N T R I B U T I O N	COST ADVERSE PARENT MISSION FACTORS FAILURE PATTERNS CONSUMPTION DISSIPATION MASS / WEIGHT VOLUME / SHAPE, ETC				
	NET CONTRIBUTION				

10/20/07

Rigorous Soft Method



- So far, we have
 - identified problem symptoms,
 - grouped them into problem themes,
 - modelled an ideal world (N2 chart, etc.),
 - identifieddifferences SID.
- We have used *parts* of the GRM, only
- We have yet to generate criteria for a good solution...

Solution Concept Options

- Only GRM (Function) and GRM Behaviour) used so far: GRM (Form) outstanding—identifies power, structures...
- Now able to posit optional (physical) solution concepts
- Idea is emerging of a highly mobile and transportable land force
- May be air-inserted near scene of activity
- Makes extensive use of UMAs
- Concept not dissimilar to a naval task force formed around an aircraft carrier
- Carrier aircraft recce., defend fleet, mount attacks ahead of fleet.
- Carrier vulnerable, however considerable effort expended to defend it

Solution Concept Options

- Land force 2010 could be:
- Formed around a "carrier" able to launch and retrieve UMAs while on the move. Other fighting vehicles/aircraft needed to defend carrier
- Or, could comprise several vehicles, some able to launch, others able to retrieve, with yet others able to control functional split. Other fighting vehicles to defend UAV core force.
- Or, could comprise a number of semi-autonomous vehicles, each able to move, fight, launch, control and retrieve own UAVs.

Solution Concept Options (Cont.)

- Many more options to consider.
- What if the UMA's cannot get airborne, cannot see, get shot down? Can the terrestrial vehicles find the enemy, engage and defend themselves?
- What about survivability?
 - Avoidance of detection?
 - stealth, camouflage, terrain following, passive radars, "noise" CNI radios
 - Self defence?
 - New CIWS: new guided-energy weapon—multiple simultaneous engagements, doubles as attack weapon, beams reflected off mirrors on Blue UMAs
 - Damage tolerance?
 - Light-weight active armour, multiple redundancy at vehicle and systems levels, self-healing systems, 0n-the-move damage repair teams...

Task

- Consider each of the optional solutions, and one other of your own
- Develop a distinct CONOPS for each, highlighting any differences.
- Are you able to identify the relative strengths and weaknesses of the options
 - How well? How sure are you?
- Are you able to choose which you prefer?
 - How firm is your choice?
 - Could you *prove* (e.g. to your boss) that your choice is the best?
- Could there be much better, quite different options? How would we know? How could we find out?

Codifying Conception

Scope, populate and explore **CONOPS** problem space Develop Simulate Solution solution solution emergent concept map concept behavior Identify Group implicit systems/functions functions/systems/ Functional processes: minimize processes implied architecture by causal links configuration entropy Instantiate GRM: Develop functional Function systems solution Behavior model • Form Develop Link models to Create full environment and create dynamic systems solution interacting interactive model systems models systems model - from 2 Adjust System Subsystems subsystems and solution emergent properties, optimizing interactions to capabilities, optimize EPCS and behaviors criteria 13 System solution -System emergent properties, capabilities, solution and behaviors

Route Map

From problem space to system solution